

Fig.1

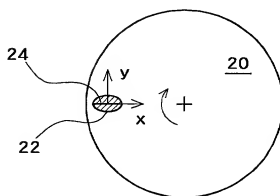


Fig.2

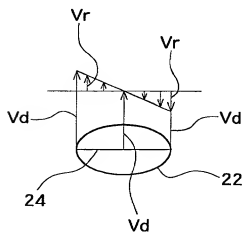


Fig.3

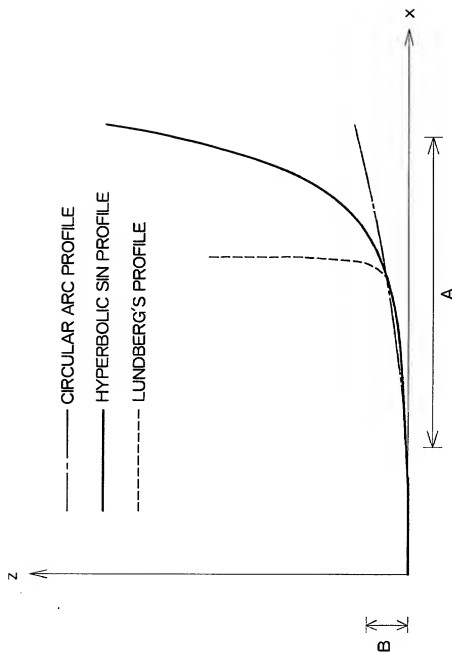


Fig.4

208320-ENG/5001

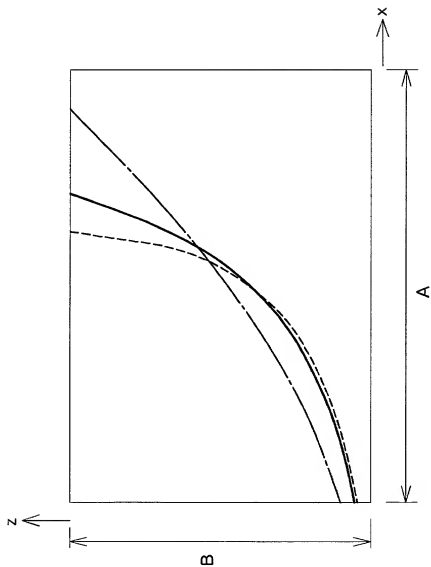


Fig.5

20250320: 20679001

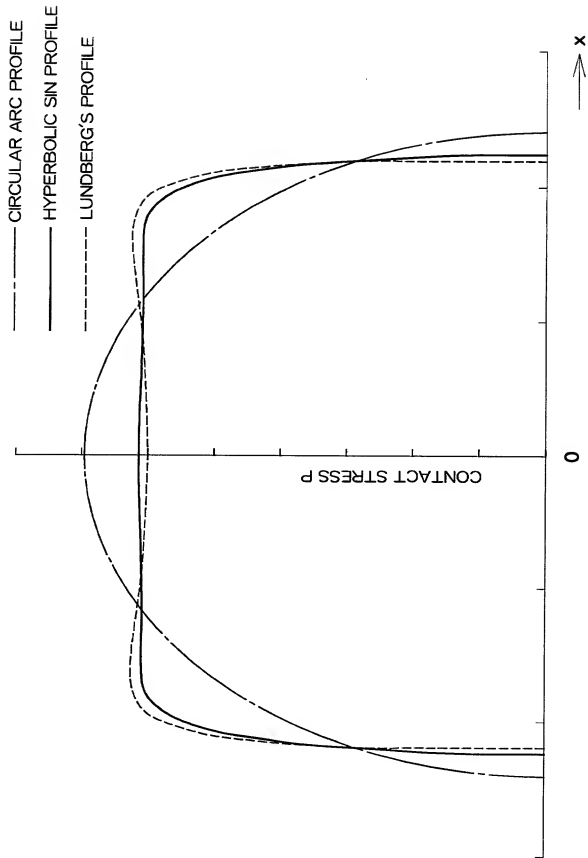
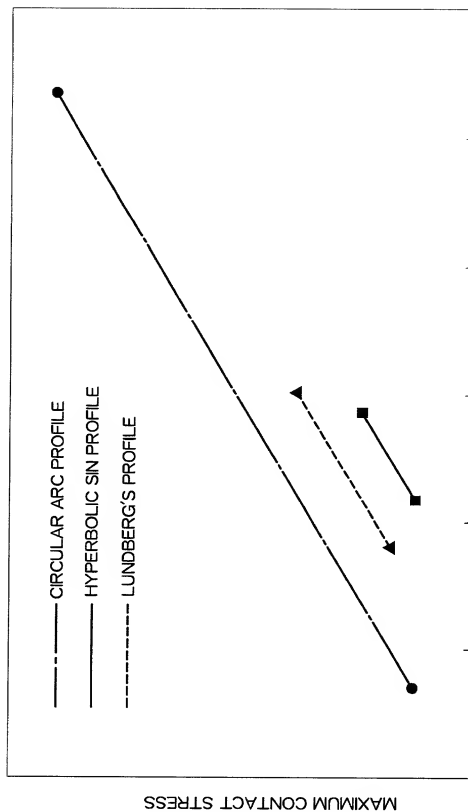


Fig.6

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Fig.7

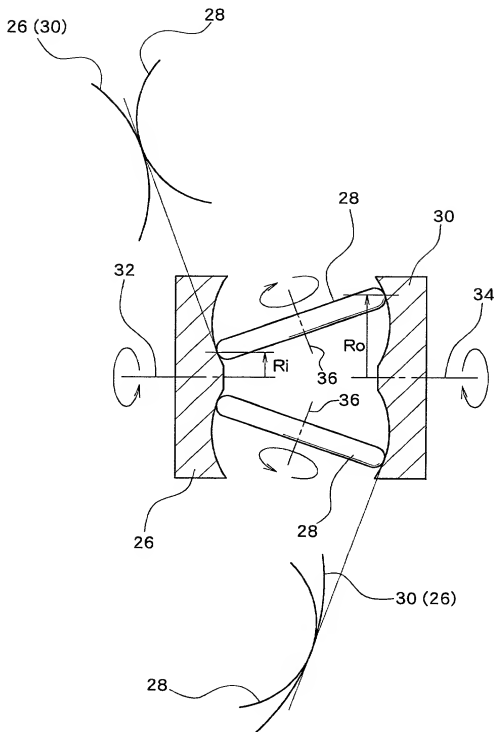


Fig.8

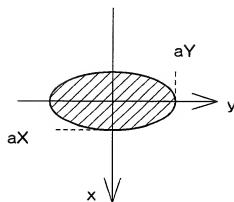


Fig.9

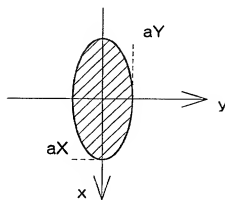


Fig.10

10067903.020002

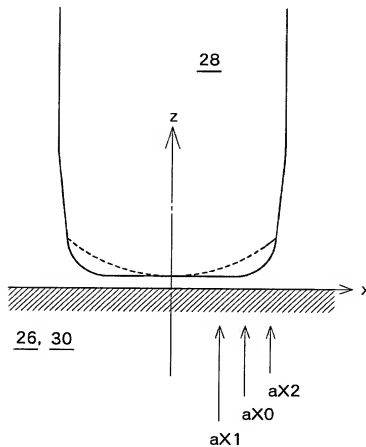


Fig.11



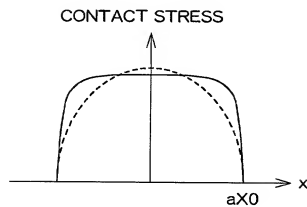


Fig. 12

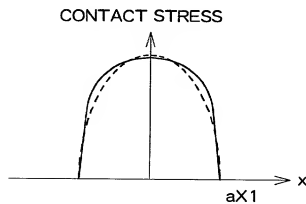


Fig. 13

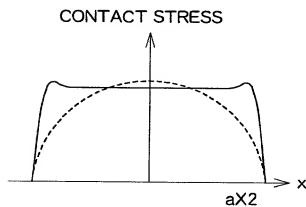
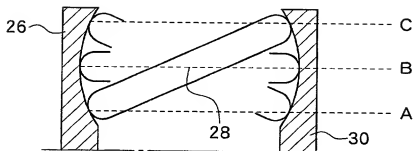


Fig. 14

10067503.020802



SPEED CHANGING STATE	INPUT CONTACT	OUTPUT CONTACT
DECELERATION	A	C
CONSISTENT SPEED	B	B
ACCELERATION	C	A

Fig.15

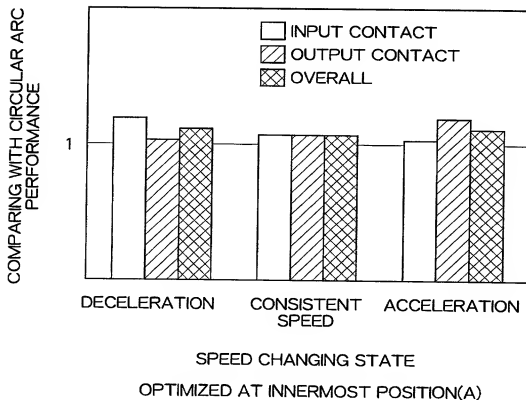


Fig.16

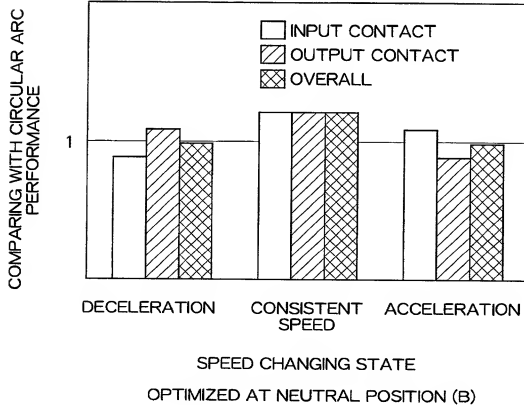


Fig.17

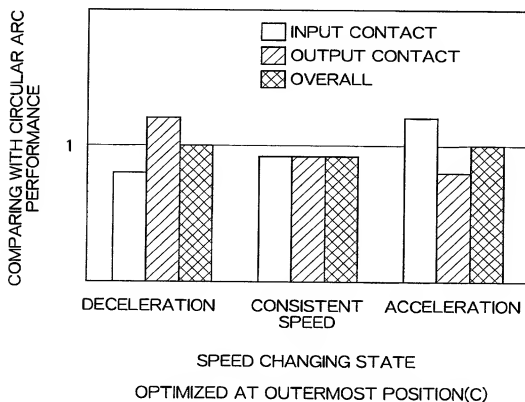


Fig.18

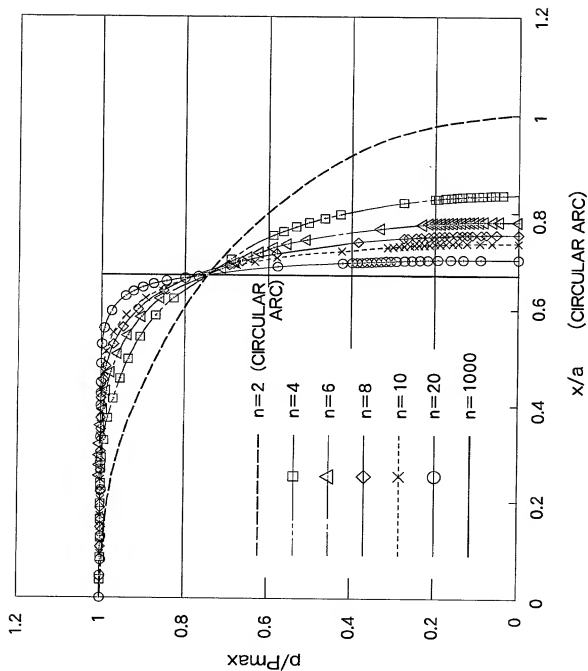


Fig.19

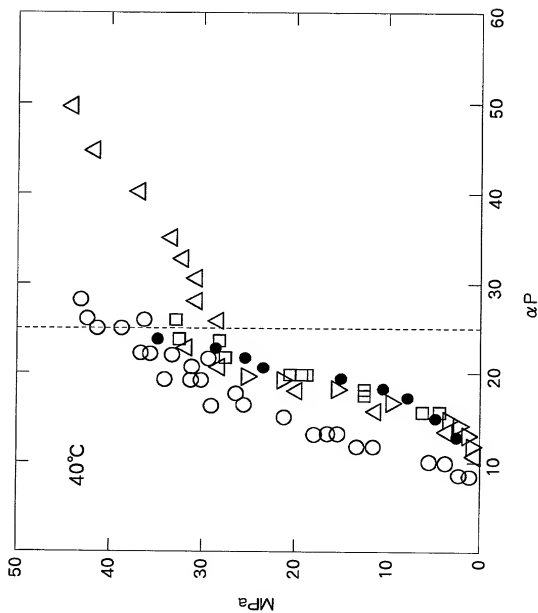


Fig.2.0

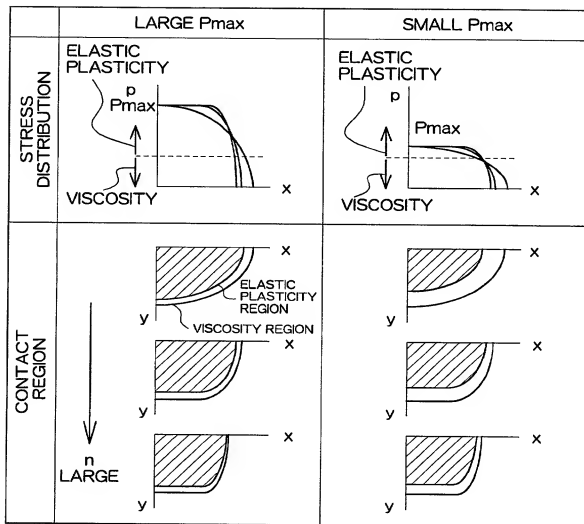


Fig.21

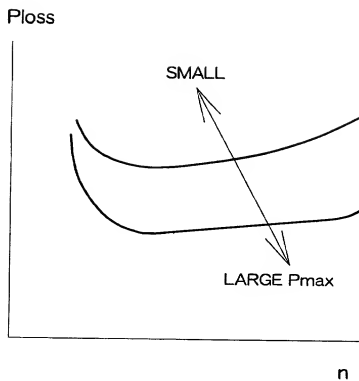


Fig.22

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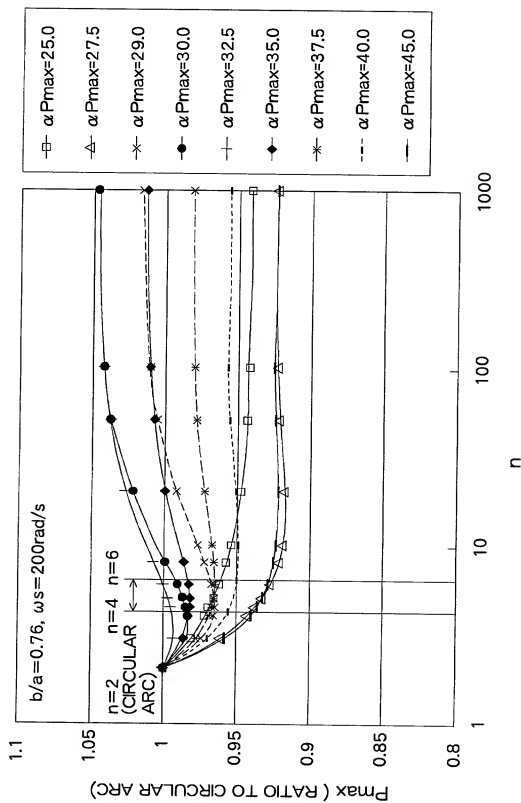


Fig.23



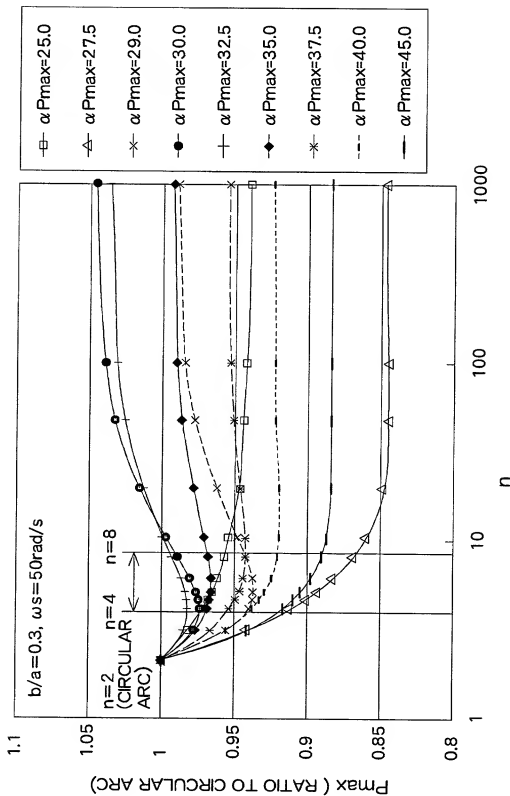


Fig.24

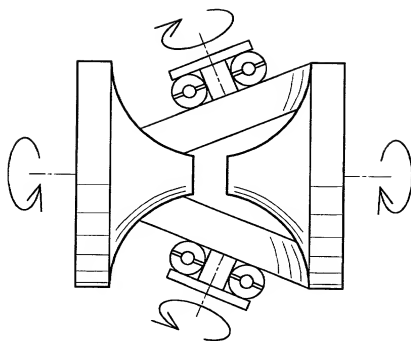


Fig.25

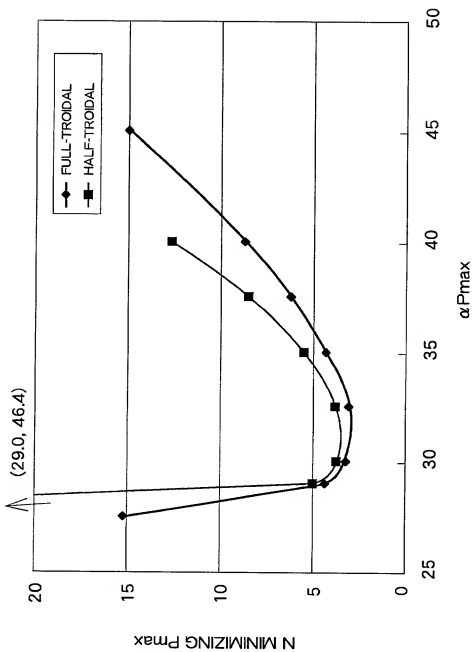


Fig.26

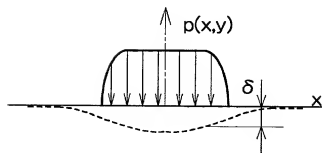
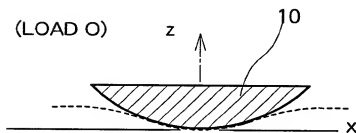


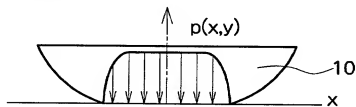
Fig.27A



16

Fig.27B

(LOAD W)



16

Fig.27C

10067303.020002

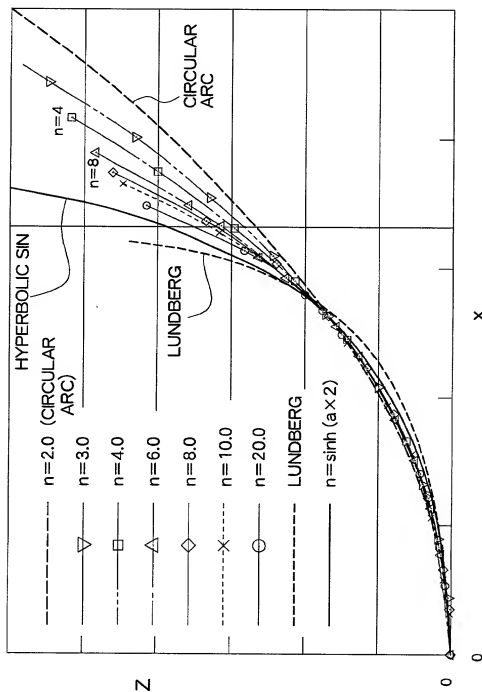


Fig.28